

**AMENDMENTS TO THE CLAIMS:**

Please cancel claims 8-12, 16-19, 22-30, 33-40, 43, 44, 50, and 56-60, amend claim 41, and add new claims 65-66, as listed in the following listing of the claims, which replaces all prior versions and listings of claims in the application:

1. (Original) A method of producing variable rate filtered samples for use as data in a secondary process that has prescribed time intervals during which filtered samples are required, comprising:

producing multiple respective periodic sequences of filtered samples each having a same sample period, wherein each respective sequence can provide a different filtered sample during each sample period and the respective sequences are offset in time with respect to one another so that no filtered sample from any sequence overlaps with any filtered sample from any other sequence; and

selecting from among the respective sequences filtered samples that coincide with the timing requirements of the secondary process.

2. (Original) The method of claim 1, wherein selecting is done from at least one of the respective sequences.

3. (Original) The method of claim 1, wherein selecting is done from at least two of the respective sequences.

4. (Original) The method of claim 1, wherein selecting is done from at least three of the respective sequences.
5. (Original) The method of claim 1, wherein selecting is done from at least four of the respective sequences.
6. (Original) The method of claim 1, wherein selecting is performed sequentially and periodically from at least two of the respective sequences.
7. (Original) The method of claim 1, wherein:  
each respective sequence has a same filter sampling time;  
selecting is performed every prescribed time interval; and  
the same filter sampling time is less than the prescribed time interval.
8. (Canceled)
9. (Canceled)
10. (Canceled)

11. (Canceled)

12. (Canceled)

13. (Original) The method of claim 1, wherein the sequences have a quantity equal to a value governed by the expression: value = maximum of  $\{(T_f/T_{be})^*n$ , for all allowable  $T_{be}\}$ , where  $n$  is a smallest integer that will result in an integer value for  $(T_f/T_{be})^*n$ ,  $T_f$  is a filter sampling time and  $T_{be}$  is a prescribed time interval.

14. (Original) The method of claim 13, wherein selecting is performed every prescribed time interval, further comprising changing the prescribed time interval  $T_{be}$ .

15. (Original) The method of claim 1, wherein selecting is performed every prescribed time interval, further comprising changing the prescribed time interval  $T_{be}$ , wherein the prescribed time interval  $T_{be}$  comprises a blanking time  $T_b$  and an exposure time  $T_e$  and changing the prescribed time interval  $T_{be}$  comprises increasing the exposure time  $T_e$ .

16. (Canceled)

17. (Canceled)

18. (Canceled)

19. (Canceled)

20. (Original) A method of generating at a variable rate a filtered output using a synchronous filter, wherein the filtered output is accepted periodically by a secondary process with a secondary process period  $T_{be}$  and the synchronous filter generates the filtered output with a filter sampling time  $T_f$ , comprising:

changing the filter sampling time  $T_f$  of the synchronous filter such that the synchronous filter generates the filtered output when the secondary process is able to periodically accept the filtered output;

accepting a sensor sample by the synchronous filter;

generating the filtered output from the synchronous filter using the sensor sample; and

accepting the filtered output by the secondary process.

21. (Original) The method of claim 20, wherein the synchronous filter also generates the filtered output when the secondary process is unable to periodically accept the filtered output.

22. (Canceled)

23. (Canceled)

24. (Canceled)

25. (Canceled)

26. (Canceled)

27. (Canceled)

28. (Canceled)

29. (Canceled)

30. (Canceled)

31. (Original) A method of generating at a variable rate a filtered output using a synchronous filter, wherein the filtered output is accepted periodically by a secondary

process with a secondary process period  $T_{be}$  and the synchronous filter generates the filtered output with a filter sampling time  $T_f$ , comprising:

increasing the secondary process period  $T_{be}$  by an amount such that the secondary process is able to periodically accept the filtered output at substantially the same time the synchronous filter produces the filtered output;

accepting a sensor sample by the synchronous filter;

generating the filtered output from the synchronous filter using the sensor sample; and

accepting the filtered output by the secondary process.

32. (Original) The method of claim 31, wherein the synchronous filter also generates the filtered output when the secondary process is unable to periodically accept the filtered output.

33. (Canceled)

34. (Canceled)

35. (Canceled)

36. (Canceled)

37. (Canceled)

38. (Canceled)

39. (Canceled)

40. (Canceled)

41. (Currently Amended) A system for use with a secondary process that requires different filtered samples during each of a sequence of input window time intervals, and for providing filtered electronic signal samples, comprising:

multiple filtered sample lines;

multiple filters, each periodically receiving a sample of a signal; wherein:

each filter periodically provides its filtered sample sequence to a filtered sample line with a respective filter sampling time  $T_f$ , and

the respective filtered sample sequences are offset in time with respect to one ~~another~~ another so that no filtered sample from any filtered sample sequence overlaps with any filtered sample from any other filtered sample sequence;

a multiplexer responsive to control signals and coupled to each of the multiple filtered sample lines; wherein:

the multiplexer accepts the respective periodic filtered output of each of the multiple filters, and

the multiplexer has a multiplexer output; and

control logic providing control signals causing the multiplexer to:

select from among the filtered sample lines in a sequence results in respective coincidences of respective filtered samples on respective selected filtered sample lines and respective input sample windows for the secondary process, and sequentially provide respective filtered samples on respective selected lines as a sequence of filtered input for use by the secondary process.

42. (Original) The system of claim 41, wherein the sequence of filtered input is produced using less than all of the respective filtered sample sequences accepted by the multiplexer.

43. (Canceled)

44. (Canceled)

45. (Original) The system of claim 41, further comprising a sensor that generates the signal.



46. (Original) The system of claim 45, further comprising an analog-to-digital converter that periodically generates the sample of the signal.
47. (Original) The system of claim 46, wherein the sample is indicative of a position of a stage assembly.
48. (Original) The system of claim 47, wherein the stage assembly positions at least one reticle.
49. (Original) The system of claim 47, wherein the stage assembly positions at least one wafer.
50. (Canceled)
51. (Original) The system of claim 41, wherein:  
the secondary process has a prescribed time interval  $T_{be}$  by which the input sample windows are spaced; and  
the prescribed time interval  $T_{be}$  is less than the filter sampling time  $T_f$ .
52. (Original) The system of claim 41, wherein:  
the multiple filters are programmable filters; and

the respective filter sampling time of each programmable filter can be changed.

53. (Original) The system of claim 41, wherein:

the secondary process has a prescribed time interval  $T_{be}$  by which the input sample windows are spaced;

the prescribed time interval  $T_{be}$  has multiple allowable values; and

the multiple filters have a quantity equal to a value governed by an expression:  
value = {maximum of  $(T_f/T_{be}) * n$ , for all allowable  $T_{be}$ }, where  $n$  is a smallest integer that will result in an integer value for  $(T_f/T_{be}) * n$ .

54. (Original) A lithography source control system comprising:

a sensor generating a signal;

multiple filters each periodically accepting a sample of the signal and producing a respective periodic filtered output with a filter sampling time  $T_f$ ;

a multiplexer having a multiplexer output and accepting the respective periodic filtered output of each of the multiple filters;

control logic controlling the multiplexer such that the multiplexer output produces an output sequence of the respective periodic filtered output accepted by the multiplexer; and

a lithography source that is controlled using the output sequence.

55. (Original) The system of claim 54, wherein the output sequence is produced using less than all of the respective periodic filtered outputs accepted by the multiplexer.

56. (Canceled)

57. (Canceled)

58. (Canceled)

59. (Canceled)

60. (Canceled)

61. (Original) The system of claim 54, wherein a prescribed time interval  $T_{be}$  is less than the filter sampling time  $T_f$ .

62. (Original) The system of claim 54, wherein:  
the multiple synchronous filters have a quantity;  
the sequence is a periodic sequence with a prescribed time interval  $T_{be}$  having multiple allowable values; and

the quantity is equal to a value governed by an expression: value = maximum of  $\{(T_f/T_{be})^*n$ , for all allowable  $T_{be}\}$ , where  $n$  is a smallest integer that will result in an integer value for  $(T_f/T_{be})^*n$ .

63. (Original) A method of exposing a wafer to an electron beam in a microlithography apparatus, comprising:

acquiring, from a sensor, data indicative of a position of a stage assembly that positions the wafer;

calculating, from the data, a velocity of the stage assembly and an acceleration of the stage assembly;

estimating, using the velocity and the acceleration, a future position of the stage assembly;

determining a difference between the position and the future position; and

adjusting at least one of:

the position within a predetermined position error, and

a deflection amount of the electron beam.

64. (Original) The method of claim 63, wherein acquiring comprises asynchronous data acquisition.

65. (New) An electron beam lithography system, comprising:

an electron optical column;  
a wafer stage moving while a pattern is being exposed;  
a sensor for detecting the position of the wafer stage and producing the signal about the position of the wafer stage;  
a filter-predictor combination for producing a positional error estimate from the signal of the sensor and for generating the data of the future states of the system; and  
a controller for controlling the wafer stage position based on the data from the predictor,  
wherein the filter-predictor combination employs multiple synchronous filters having outputs that are staggered in time.

66. (New) An electron beam lithography system, comprising:

an electron optical column;  
a wafer stage moving while a pattern is being exposed;  
a sensor for detecting the position of the wafer stage and producing the signal about the position of the wafer stage;  
a filter-predictor combination for producing a positional error estimate from the signal of the sensor and for generating the data of the future states of the system; and  
a controller for controlling the wafer stage position based on the data from the predictor,

wherein the filter-predictor combination employs a programmable filter having an update time that is smaller than an exposure cycle time.